

Comment on “Existence and regularity for an energy maximization problem in two dimensions” [S. Kamvissis and E. A. Rakhmanov, *J. Math. Phys.* 46, 083505 (2005)]

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DROPPING ASSUMPTION (A) IN SEC. 5 OF REF. 2

In Sec. 5 of Ref. 2, we have assumed that the solution of the problem of the maximization of the equilibrium energy is a continuum, say F , which does not intersect the linear segment $[0, iA]$ except of course at $0_+, 0_-$. We also prove that F does not touch the real line, except of course at 0 and possibly ∞ . This enables us to take variations in Sec. 6 of Ref. 2, keeping fixed a finite number of points, and thus arrive at the identity of Theorem 5 of Ref. 2, from which we derive the regularity of F and the fact that F is, after all, an S-curve.

In general, it is conceivable that F intersects the linear segment $[0, iA]$ at points other than $0_+, 0_-$. If the set of such points is finite, there is no problem, since we can always consider variations keeping fixed a finite number of points and arrive at the same result (see the remark after the proof of Theorem 5 of Ref. 2).

If, on the other hand, this is not the case, we have a different kind of problem, because the function V introduced in Sec. 6 of Ref. 2 (the complexification of the field) is not analytic across the segment $[-iA, iA]$.

What is true, however, is that V is analytic in a Riemann surface consisting of infinitely many sheets, cut along the line segment $[-iA, iA]$. So, the appropriate, underlying space for the (doubled up) variational problem should now be a noncompact Riemann surface, say L .

Compactness is crucial in the proof of a maximizing continuum. But we can compactify the Riemann surface L by compactifying the complex plane. Let the map $C \rightarrow L$ be defined by

$$y = \log(z - iA) - \log(z + iA).$$

The point $z = iA$ corresponds to infinitely many y -points, i.e., $y = -\infty + i\theta$, $\theta \in \mathbb{R}$, which will be identified. Similarly, the point $z = -iA$ corresponds to infinitely many points $y = +\infty + i\theta$, $\theta \in \mathbb{R}$, which will also be identified. The point $0 \in C$ corresponds to the points $k\pi i$, k odd.

By compactifying the plane we then compactify the Riemann surface L . The distance between two points in the Riemann surface L is defined to be the corresponding stereographic distance between the images of these points in the compactified C .

With these changes, the proof of the existence of the maximizing continuum in Secs. 1, 3, and 4 of Ref. 2 goes through virtually unaltered. In Sec. 6 of Ref. 2, we would have to consider the

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complex field V as a function defined in the Riemann surface \mathbb{L} and all proofs go through. The corresponding result of Sec. 7 of Ref. 2 will give us an S-curve C in the Riemann surface \mathbb{L} . We then have the following facts.

Consider the image \mathbb{D} of the closed upper half-plane under

$$y = \log(z - iA) - \log(z + iA).$$

Consider continua in \mathbb{D} containing the points $y = \pi i$ and $y = -\pi i$. Define Green's potential and Green's energy of a Borel measure by (4)–(6) of Ref. 2 and the equilibrium measure by (7) of Ref. 2. Then there exists a continuum F maximizing the equilibrium energy, for the field given by (3) of Ref. 2 with conditions (1) of Ref. 2. F does not touch $\partial\mathbb{D}$ except at a finite number of points. By taking variations as in Sec. 6 of Ref. 2, one sees that F is an S-curve. In particular, the support of the equilibrium measure on F is a union of analytic arcs and at any interior point of $\text{supp } \mu$,

$$\frac{d}{dn_+}(\phi + V^{\lambda^F}) = \frac{d}{dn_-}(\phi + V^{\lambda^F}),$$

where the two derivatives above denote the normal derivatives.

We then have the following.

Theorem (Theorem 9 of Ref. 2) Consider the semiclassical limit ($\hbar \rightarrow 0$) of the solution of (9) and (10) of Ref. 2 (that is, the initial value problem for the focusing NLS with parameter \hbar) with bell-shaped initial data. Replace the initial data by the so-called soliton ensembles data (as introduced in Ref. 1) defined by replacing the scattering data for $\psi(x, 0) = \psi_0(x)$ by their WKB approximation. Assume, for simplicity, that the spectral density of eigenvalues satisfies conditions (1) of Ref. 2.

Then, asymptotically as $h \rightarrow 0$, the solution $\psi(x, t)$ admits a “finite genus description,” in the sense of Theorem A.1 of Ref. 2.

Proof:

- (i) The proof of the existence of an S-curve F in \mathbb{L} follows as above.
- (ii) We want to deform the original discrete Riemann–Hilbert problem to the set \hat{F} consisting of the projection of F to the complex plane. It is clear, however, that \hat{F} may not encircle the spike $[0, iA]$. It is possible, on the other hand, to append S-loops (considered in \mathbb{L}) and end up with a sum of S-loops, such that the amended \hat{F} does encircle the spike $[0, iA]$, meaning that $[0, iA]$ is a subset of the closure of the union of the interiors of the loops of which \hat{F} consists. A little thought shows that this is all we need. (Indeed, within each of the loops we use the same pole-removing transformation as in Ref. 1. Eventually of course we have to use different interpolations, according to the sheet of each piece of F .) To see that we can always append the needed S-loop, suppose there is an open interval, say $(i\alpha, i\alpha_1)$, which lies in the exterior of \hat{F} , while $i\alpha, i\alpha_1 \in \hat{F}$. Let us assume, for example, that \hat{F} crosses $[0, iA]$ along bands at $i\alpha, i\alpha_1$; call these bands S, S_1 and assume they lie in the principal sheet. Let β^-, β^+ be points (considered in \mathbb{C}) lying on S to the left and right of $i\alpha$, respectively, and at a small distance from $i\alpha$. Similarly, let β_1^-, β_1^+ be points lying on S_1 to the left and right of $i\alpha_1$, respectively, and at a small distance from $i\alpha_1$. We will show that there exists a “gap” region including the preimages of β^-, β_1^- lying in the N th sheet for $-N$ large enough, and similarly there exists a “gap” region including the preimages of β^+, β_1^+ lying in the M th sheet for M large enough, both being regions for which the gap inequalities hold *a priori*, irrespectively of the actual S-curve, depending only on the external field! Indeed, note that the quantity $\text{Re}(\tilde{\phi}^\sigma(z))$ (which defines the variational inequalities) is *a priori* bounded above by $-\phi(z)$. For this, see (8.8) in Chapter 8 of Ref. 1; there is actually a sign error: the right formula is

$$\operatorname{Re}(\tilde{\phi}^\sigma(z)) = -\phi(z) + \int G(z, \eta) \rho^\sigma(\eta) d\eta.$$

Next note [see, for example, (5.8) of Ref. 1 with K varying along the natural numbers according to the relevant sheet of \mathbb{L}] that the difference of the values of the function $\operatorname{Re}(\tilde{\phi}^\sigma(z))$ in consecutive sheets is $\delta \operatorname{Re}(\tilde{\phi}^\sigma) \sim \pm 2 \operatorname{Im} \rho(z) \pi \operatorname{Re} z$ near the spike $[0, iA]$ [remember $\operatorname{Im} \rho(z) > 0$ there] and hence the difference of the values at points on consecutive sheets whose image under the projection to the complex plane is $i\eta + \epsilon$, where η is real and ϵ is a small (negative or positive) real, is $\delta \operatorname{Re} \tilde{\phi}^\sigma \sim \pm 2\pi \operatorname{Im} \rho(z) \epsilon$. This means that on the left (right) side of the imaginary semiaxis, the inequality $\operatorname{Re}(\tilde{\phi}^\sigma(z)) < 0$ will be eventually (depending on the sheet) be valid at any given small distance to it.

We now connect the preimages of β^- and β_1^- (under the projection of \mathbb{L} to \mathbb{C}) lying in the N th sheet to the preimages of β^- and β_1^- lying in the principal sheet respectively, using the results of Ref. 2. Similarly we join the preimages of β^+ and β_1^+ lying in the M th sheet to the preimages of β^+ and β_1^+ lying in the principal sheet respectively.

Then, we join the the preimages of β^- and β_1^- (under the projection of \mathbb{L} to \mathbb{C}) lying in the N th sheet and the preimages of β^+ and β_1^+ lying in the M th sheet, along the according gap regions.

It is easy to see that (together with the bands S and S_1) we end up with an S-loop (in \mathbb{L}) whose projection is covering the “lacuna” $(i\alpha, i\alpha_1)$.

The original discrete Riemann–Hilbert problem can be trivially deformed to a discrete Riemann–Hilbert on the resulting (projection of the) union of S-loops. All this is possible even in the case where \hat{F} self-intersects.

- (iii) We deform the discrete Riemann–Hilbert problem to the continuous one with the right band/gap structure (on \hat{F} ; according to the equilibrium measure on F), which is then explicitly solvable via theta functions exactly as in Ref. 1. Both the discrete-to-continuous approximation and the opening of the lenses needed for this deformation are justified as in Ref. 1 and therefore the technical details will not be repeated here. It is important to notice that our construction has ensured the analytic continuation of the jump matrix along \hat{F} (oriented according to F). The g -function is defined by the same Thouless-type formula with respect to the equilibrium measure (cf. Sec. 2(iii)). It satisfies the same conditions as in Ref. 1 (measure reality and variational inequality) on bands and gaps. The equilibrium measure lives in \mathbb{L} but the Riemann–Hilbert problem lives in \mathbb{C} .

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